# On the approximate Jacobian Newton diagrams of an irreducible plane curve 

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#### Abstract

We introduce the notion of an approximate Jacobian Newton diagram which is the Jacobian Newton diagram of the morphism $\left(f^{(k)}, f\right)$, where $f$ is a branch and $f^{(k)}$ is a characteristic approximate root of $f$. We prove that the set of all approximate Jacobian Newton diagrams is a complete topological invariant. This generalizes theorems of Merle and Ephraim about the decomposition of the polar curve of a branch.


## 1. Introduction.

Every two complex series $f, g \in \boldsymbol{C}\{x, y\}$ such that $f(0,0)=g(0,0)=0$ define a germ of a holomorphic mapping $(g, f):\left(\boldsymbol{C}^{2}, 0\right) \longrightarrow\left(\boldsymbol{C}^{2}, 0\right)$. Assume that the curves $f=0$ and $g=0$ share no common component. Then the critical locus of this mapping is a germ of an analytic curve and its direct image by $(g, f)$ is also an analytic curve called the discriminant curve. Let $D(u, v)=0$ be an equation of the discriminant curve in the coordinates $(u, v)=(g(x, y), f(x, y))$. We call the Newton diagram of $D(u, v)$ the Jacobian Newton diagram of the morphism $(g, f)$ and denote it $\mathcal{N}_{J}(g, f)$.

Note that if $g=0$ is a smooth curve transverse to $f=0$ then $\mathcal{N}_{J}(g, f)$ is the Jacobian Newton diagram of the curve $f=0$ introduced in [Te3]. With these assumptions Teissier proves in $[\mathbf{T e} \mathbf{1}]$ that $\mathcal{N}_{J}(g, f)$ depends only on the topological type of the curve $f=0$.

Merle in $[\mathrm{Me}]$ studies the case of a smooth curve $g=0$ transverse to an irreducible singular curve $f=0$. He gives a description of the Jacobian Newton diagram in terms of other invariants of singularity of a curve $f=0$. He also shows that the datum of the Jacobian Newton diagram determines the equisingularity class of the curve (or equivalently its embedded topological type). Ephraim in [Eph] extends Merle's result to any smooth curve $g=0$.

Let $f$ be an irreducible Weierstrass polynomial. In this paper we generalize the results of Merle to the family $\left\{\mathcal{N}_{J}\left(f^{(k)}, f\right)\right\}_{k}$, where $f^{(k)}$ is the $k$-th characteristic

[^0]approximate root of $f$ introduced in $[\mathbf{A}-\mathbf{M}]$. We prove, in two different ways, that this family is a complete topological invariant of the branch $f=0$. Our computations are based on the decomposition of the critical locus of the mapping $\left(f^{(k)}, f\right)$, which is analogous to the decomposition of the polar curve obtained by Merle in [Me].

## 2. Plane branches, semigroup and approximate roots.

We mean by the fractional power series the elements of the ring $\boldsymbol{C}\{x\}^{*}=$ $\bigcup_{n \in N} \boldsymbol{C}\left\{x^{1 / n}\right\}$. For every two fractional power series $\delta$ and $\delta^{\prime}$ we call the number $\mathcal{O}\left(\delta, \delta^{\prime}\right)=\operatorname{ord}_{x}\left(\delta(x)-\delta^{\prime}(x)\right)$ the contact order between $\delta$ and $\delta^{\prime}$.

Every convergent power series $g(x, y) \in \boldsymbol{C}\{x, y\}, g(0,0)=0$ has the NewtonPuiseux factorization

$$
g(x, y)=u(x, y) x^{N} \prod_{i=1}^{d}\left(y-\gamma_{i}(x)\right)
$$

where $u(x, y) \in \boldsymbol{C}\{x, y\}, u(0,0) \neq 0, N$ is a nonnegative integer and $\gamma_{i}(x)$ are fractional power series of positive order. We will call $\gamma_{i}$ the Newton-Puiseux roots of $g$ and denote the set $\left\{\gamma_{1}, \ldots, \gamma_{d}\right\}$ by Zer $g$.

Let $f(x, y)$ be an irreducible power series such that $\operatorname{ord}_{y}(f(0, y))=n \geq 1$. Then $f$ has a Newton-Puiseux root of the form $\gamma_{1}(x)=\sum_{i=1}^{\infty} a_{i} x^{i / n}$. The other Newton-Puiseux roots are $\gamma_{j}(x)=\sum_{i=1}^{\infty} a_{i} \omega^{(j-1) i} x^{i / n}$ for $1 \leq j \leq n$, where $\omega \in \boldsymbol{C}$ is an $n$-th primitive root of unity. The contact orders between the elements of Zer $f$ form a set $\left\{b_{1} / n, \ldots, b_{g} / n\right\}$, where $b_{1}<b_{2}<\cdots<b_{g}$ and $\operatorname{gcd}\left(n, b_{1}, \ldots, b_{g}\right)=1$. We put $b_{0}=n$ and call the sequence $\left(b_{0}, b_{1}, \ldots, b_{g}\right)$ the Puiseux characteristic of $f$. By convention $b_{g+1}=+\infty$.

Let $A$ and $B$ be finite sets of fractional power series. The contact $\operatorname{cont}(A, B)$ is by definition $\max \{\mathcal{O}(\alpha, \beta): \alpha \in A, \beta \in B\}$. If $\alpha(x)$ is a fractional power series and $f(x, y), g(x, y)$ are irreducible power series co-prime to $x$ then by abuse of notation we will write $\operatorname{cont}(\alpha, f):=\operatorname{cont}(\{\alpha\}$, Zer $f)$ and $\operatorname{cont}(f, g):=\operatorname{cont}($ Zer $f$, Zer $g)$.

It is well-known (see for example Lemma 4.3 of [Ca1]) that for every NewtonPuiseux root $\alpha$ of $f$ we have cont $(\alpha, g)=\operatorname{cont}(f, g)$. The contact between irreducible power series has a strong triangle inequality property: if $h_{i} \in \boldsymbol{C}\{x, y\}$ for $i=1,2,3$ are irreducible power series co-prime to $x$ then $\operatorname{cont}\left(h_{1}, h_{2}\right) \geq$ $\min \left(\operatorname{cont}\left(h_{1}, h_{3}\right), \operatorname{cont}\left(h_{2}, h_{3}\right)\right)$.

In $[\mathbf{A}-\mathbf{M}]$ the authors introduce the concept of the approximate root as a consequence of the following proposition:

Proposition 1. Let $\boldsymbol{A}$ be an integral domain. If $f(y) \in \boldsymbol{A}[y]$ is monic of
degree $d$ and $p$ is invertible in $\boldsymbol{A}$ and divides $d$, then there exists a unique monic polynomial $g(y) \in \boldsymbol{A}[y]$ such that the degree of $f-g^{p}$ is less than $d-d / p$.

This allows us to define:
Definition 1. The unique monic polynomial of the preceding proposition is called the $p$-th approximate root of $f$.

Let $f \in \boldsymbol{C}\{x\}[y]$ be an irreducible Weierstrass polynomial with Puiseux characteristic $\left(b_{0}, \ldots, b_{g}\right)$. Put $l_{k}:=\operatorname{gcd}\left(b_{0}, \ldots, b_{k}\right)$. In particular $l_{k}$ divides $\operatorname{deg} f=b_{0}$ for all $k \in\{0, \ldots, g\}$. In the sequel for $k \in\{0, \ldots, g-1\}$ we denote $f^{(k)}$ the $l_{k}$-th approximate root of $f$ and we call these polynomials the characteristic approximate roots of $f$. By convention we put $f^{(-1)}=x$.

The following proposition is the main one in $[\mathbf{A}-\mathbf{M}]$ (see also [G-Pł2] and [Po]):

Proposition 2. Let $f \in \boldsymbol{C}\{x\}[y]$ be an irreducible Weierstrass polynomial with Puiseux characteristic $\left(b_{0}, \ldots, b_{g}\right)$. Then the characteristic approximate roots $f^{(k)}$ for $k \in\{0, \ldots, g-1\}$, have the following properties:

1. The polynomial $f^{(k)}$ is irreducible with Puiseux characteristic $\left(b_{0} / l_{k}, \ldots, b_{k} / l_{k}\right)$.
2. The $y$-degree of $f^{(k)}$ is equal to $b_{0} / l_{k}$ and $\operatorname{cont}\left(f, f^{(k)}\right)=b_{k+1} / b_{0}$.

Example 1. Take the irreducible Weierstrass polynomial $f=\left(y^{3}-6 x^{3} y-\right.$ $\left.x^{4}\right)^{2}-9 x^{9}$ of Puiseux characteristic $(6,8,11)$. The characteristic approximate roots of $f$ are $f^{(0)}=y$ and $f^{(1)}=y^{3}-6 x^{3} y-x^{4}$. The Newton-Puiseux roots of $f$ are of the form $y=\omega^{8} x^{4 / 3}+2 \omega^{10} x^{5 / 3}+\omega^{11} x^{11 / 6}+\cdots$, where $\omega^{6}=1$ while the NewtonPuiseux roots of $f^{(1)}$ are $y=\epsilon^{4} x^{4 / 3}+2 \epsilon^{5} x^{5 / 3}-(8 / 3) x^{2}+\cdots$, where $\epsilon^{3}=1$. One can check directly that $\operatorname{cont}\left(f, f^{(0)}\right)=8 / 6$ and $\operatorname{cont}\left(f, f^{(1)}\right)=11 / 6$.

## 3. Jacobian Newton diagrams.

In this section we recall the notion of the Jacobian Newton diagrams and we establish some preliminary results which are necessary for the next.

Write $\boldsymbol{R}_{+}=\{x \in \boldsymbol{R}: x \geq 0\}$. Let $f \in \boldsymbol{C}\{x, y\}, f(x, y)=\sum a_{i, j} x^{i} y^{j}$ be a non-zero convergent power series. Put $\operatorname{supp} f:=\left\{(i, j): a_{i, j} \neq 0\right\}$ the support of $f$. By definition the Newton diagram of $f$ in the coordinates $(x, y)$ is

$$
\Delta_{f}:=\text { Convex Hull }\left(\operatorname{supp} f+\boldsymbol{R}_{+}^{2}\right)
$$

An important property of Newton diagrams is that the Newton diagram of a product is the Minkowski sum of Newton diagrams. One has $\Delta_{f g}=\Delta_{f}+\Delta_{g}$,
where $\Delta_{f}+\Delta_{g}=\left\{a+b: a \in \Delta_{f}, b \in \Delta_{g}\right\}$. In particular if $f$ and $g$ differ by an invertible factor $u \in C\{x, y\}, u(0,0) \neq 0$ then $\Delta_{f}=\Delta_{g}$. Thus the Newton diagram of a plane analytic curve is well defined because an equation of an analytic curve is given up to invertible factor, where an analytic plane curve is a principal ideal of the ring of convergent power series $\mathbf{C}\{x, y\}$, which we will denote by $f(x, y)=0$. We will write $\Delta_{f=0}$ for the Newton diagram of the curve $f=0$.

Following Teissier [Te2] we introduce elementary Newton diagrams. For $m, n>0$ we put $\left\{\frac{n}{m}\right\}=\Delta_{x^{n}+y^{m}}$. We put also $\left\{\frac{n}{\infty}\right\}=\Delta_{x^{n}}$ and $\left\{\frac{\infty}{m}\right\}=\Delta_{y^{m}}$.

Every Newton diagram $\Delta \subsetneq \boldsymbol{R}_{+}^{2}$ has a unique representation $\Delta=\sum_{i=1}^{r}\left\{\frac{L_{i}}{M_{i}}\right\}$, where inclinations of successive elementary diagrams form an increasing sequence (by definition the inclination of $\left\{\frac{L}{M}\right\}$ is $L / M$ with the conventions that $L / \infty=0$ and $\infty / M=+\infty)$. We shall call this representation the canonical decomposition of $\Delta$.

Let $\sigma=(g, f):\left(\boldsymbol{C}^{2}, 0\right) \rightarrow\left(\boldsymbol{C}^{2}, 0\right)$ be an analytic mapping given by $\sigma(x, y)=$ $(g(x, y), f(x, y)):=(u, v)$ and such that $\sigma^{-1}(0,0)=\{(0,0)\}$. Then every local analytic curve $h(x, y)=0$ has a well-defined direct image $\sigma^{*}(h=0)$ which is an analytic curve in the target space (see [Ca2]). The Newton diagram of the direct image is characterized by two properties:

1. If $h$ is an irreducible power series then $\Delta_{\sigma^{*}(h=0)}=\left\{\frac{(f, h)_{0}}{(g, h)_{0}}\right\}$, where $(r, s)_{0}$ denotes the intersection multiplicity of the curves $r=0$ and $s=0$ at the origin.
2. If $h=h_{1} h_{2}$ then $\Delta_{\sigma^{*}(h=0)}=\Delta_{\sigma^{*}\left(h_{1}=0\right)}+\Delta_{\sigma^{*}\left(h_{2}=0\right)}$.

Let $\operatorname{jac}(g, f)=\partial g / \partial x \cdot \partial f / \partial y-\partial g / \partial y \cdot \partial f / \partial x$ be the Jacobian determinant of the mapping $\sigma$. The direct image (see Preliminaries in [Ca2]) of jac $(g, f)=0$ by $\sigma$ is called the discriminant curve. We will write $\mathcal{N}_{J}(g, f)$ for the Newton diagram of the discriminant curve and following Teissier (see [Te3]) call it the Jacobian Newton diagram of the morphism $\sigma=(g, f)$.

## 4. Approximate Jacobian Newton diagrams of a branch.

In this section we introduce the notion of the approximate Jacobian Newton diagrams of an irreducible plane curve and we compute them. In what follows a branch $f(x, y)=0$ will be given by an irreducible Weierstrass polynomial.

Let $f$ be an irreducible Weierstrass polynomial and let $f^{(k)}$, for $0 \leq k \leq$ $g-1$, be the characteristic approximate roots of $f$. The Jacobian Newton diagram $\mathcal{N}_{J}\left(f^{(k)}, f\right)$ is called the $k$-th approximate Jacobian Newton diagram of the branch $f(x, y)=0$.

The following result about the factorization of the $\operatorname{Jacobian} \operatorname{jac}\left(f^{(k)}, f\right)$ is the main result of this note:

Theorem 1. Let $f \in \boldsymbol{C}\{x\}[y]$ be an irreducible Weierstrass polynomial with

Puiseux characteristic $\left(b_{0}, \ldots, b_{g}\right)$. Let $f^{(k)}, 0 \leq k \leq g-1$, be the $k$-th characteristic approximate root of $f$. Then the Jacobian $\operatorname{jac}\left(f^{(k)}, f\right)$ admits a factorization

$$
\operatorname{jac}\left(f^{(k)}, f\right)=\Gamma^{(k+1)} \cdots \Gamma^{(g)},
$$

where the factors $\Gamma^{(i)}$ are not necessary irreducible, $x$ is co-prime to the product $\Gamma^{(k+2)} \cdots \Gamma^{(g)}$ and such that

1. If $\alpha$ is a Newton-Puiseux root of $\Gamma^{(k+1)}$ then $\operatorname{cont}(\alpha, f)<b_{k+1} / b_{0}$.
2. If $\alpha$ is a Newton-Puiseux root of $\Gamma^{(i)}, k+2 \leq i \leq g$ then $\operatorname{cont}(\alpha, f)=b_{i} / b_{0}$.
3. The intersection multiplicity $\left(\Gamma^{(i)}, x\right)_{0}=n_{1} \cdots n_{i-1}\left(n_{i}-1\right)$ for $k+2 \leq i \leq g$.

The proof of Theorem 1 will be done in Section 5.
The contacts between Newton-Puiseux roots of $\Gamma^{(k+1)}$ and $f$ are not determined by the Puiseux characteristic of $f$ as the following example shows.

Example 2. Let $f=\left(y^{3}-6 x^{3} y-x^{4}\right)^{2}-9 x^{9}$ be the Weierstrass polynomial from Example 1 and let $g=\left(y^{3}-x^{4}\right)^{2}+x^{9}-x^{7} y^{2}$. Both series $f$ and $g$ are irreducible with the same Puiseux characteristic $(6,8,11)$. The Jacobian $\operatorname{jac}\left(f^{(1)}, f\right)=243 x^{8}\left(y^{2}-2 x^{3}\right)$ has two Newton-Puiseux roots $\alpha_{1}(x)=\sqrt{2} x^{3 / 2}+\cdots$, $\alpha_{2}(x)=-\sqrt{2} x^{3 / 2}+\cdots$ and $\operatorname{cont}\left(\alpha_{i}, f\right)=4 / 3<b_{2} / b_{0}$ for $i=1,2$.

On the other hand there are four Newton-Puiseux roots $\beta_{1}(x)=0, \beta_{2}(x)=$ $(8 / 27) x^{2}+\cdots, \beta_{3}(x)=\sqrt{(21 / 27)} x+\cdots, \beta_{4}(x)=-\sqrt{(21 / 27)} x+\cdots$ of $\mathrm{jac}\left(g^{(1)}, g\right)=x^{6} y\left(21 y^{3}-27 x^{2} y+8 x^{4}\right)$ and $\operatorname{cont}\left(\beta_{i}, g\right)=4 / 3$ for $i=1,2$, but $\operatorname{cont}\left(\beta_{i}, g\right)=1$ for $i=3,4$.

Further we will use the following property of the intersection multiplicity which is a consequence of the Noether's formula (see [G-Pł2, Proposition 3.3]):

Property 1. Let $g(x, y), h(x, y)$ be irreducible power series co-prime to $x$. Then for fixed $g$, the function $h \mapsto(g, h)_{0} /(x, h)_{0}$ depends only on the contact cont $(g, h)$ and is a strictly increasing function of this quantity.

Corollary 1. Under assumptions and notations of Theorem 1 the Jacobian Newton diagram of the mapping $\left(f^{(k)}, f\right)$ has the canonical decomposition

$$
\mathcal{N}_{J}\left(f^{(k)}, f\right)=\sum_{i=k+1}^{g}\left\{\frac{\left(f, \Gamma^{(i)}\right)_{0}}{\left(f^{(k)}, \Gamma^{(i)}\right)_{0}}\right\} .
$$

Proof. We prove that for every irreducible factor $h$ of $\operatorname{jac}\left(f^{(k)}, f\right)$ the quotient $(f, h)_{0} /\left(f^{(k)}, h\right)_{0}$ depends only on the contact $\operatorname{cont}(f, h)$. Indeed there
are two cases: if $\operatorname{cont}(f, h)<b_{k+1} / b_{0}$ then by the strong triangle inequality $\operatorname{cont}\left(f^{(k)}, h\right)=\operatorname{cont}(f, h)$ hence $\left(h, f^{(k)}\right)_{0} /\left(x, f^{(k)}\right)_{0}=(h, f)_{0} /(x, f)_{0}$ and we get

$$
\begin{equation*}
\frac{(f, h)_{0}}{\left(f^{(k)}, h\right)_{0}}=\frac{(x, f)_{0}}{\left(x, f^{(k)}\right)_{0}} \tag{1}
\end{equation*}
$$

if $\operatorname{cont}(f, h)>b_{k+1} / b_{0}$ then also by the strong triangle inequality $\operatorname{cont}\left(f^{(k)}, h\right)=$ $\operatorname{cont}\left(f^{(k)}, f\right)$ hence $\left(f^{(k)}, h\right)_{0} /(x, h)_{0}=\left(f^{(k)}, f\right)_{0} /(x, f)_{0}$ and we get

$$
\begin{equation*}
\frac{(f, h)_{0}}{\left(f^{(k)}, h\right)_{0}}=\frac{(x, f)_{0}}{\left(f^{(k)}, f\right)_{0}} \cdot \frac{(f, h)_{0}}{(x, h)_{0}} \tag{2}
\end{equation*}
$$

Fix $i \in\{k+1, \ldots, g\}$ and write $\Gamma^{(i)}$ as a product $h_{1} \cdots h_{r}$ of irreducible factors $h_{j}$ for $1 \leq j \leq r$. Then the Newton diagram of the direct image of the curve $\Gamma^{(i)}=0$ is the sum $\sum_{j=1}^{r}\left\{\frac{\left(f, h_{j}\right)_{0}}{\left(f^{(k)}, h_{j}\right)_{0}}\right\}$. Since all elementary Newton diagrams in the above sum have the same inclination one has

We proved that the Jacobian Newton diagram $\mathcal{N}_{J}\left(f^{(k)}, f\right)$ is the sum of elementary Newton diagrams from the statement of the Corollary. The inclination of the first elementary Newton diagram is given by formula (1) which can be written as $(x, f)_{0} /\left(f^{(k)}, f\right)_{0} \cdot\left(f, f^{(k)}\right)_{0} /\left(x, f^{(k)}\right)_{0}$. The inclinations of the remaining elementary Newton diagrams are given by formula (2). By Property 1 these inclinations form a strictly increasing sequence. This finishes the proof.

Now our aim is to give an arithmetical formula for $\mathcal{N}_{J}\left(f^{(k)}, f\right)$.
Put $\overline{b_{k}}:=\left(f, f^{(k-1)}\right)_{0}$ for $k \in\{0,1, \ldots, g\}$. Following Zariski (see $[\mathbf{Z}]$ ), the set $\left\{\overline{b_{0}}, \overline{b_{1}}, \ldots, \overline{b_{g}}\right\}$ is a minimal system of generators of the semigroup

$$
\Gamma(f):=\left\{(f, g)_{0}: f \text { is not a factor of } g\right\}
$$

of the branch $f(x, y)=0$. This system of generators is uniquely determined by the Puiseux characteristic of $f$ in the following way: $\overline{b_{0}}=b_{0}, \overline{b_{1}}=b_{1}$ and $\overline{b_{q}}=n_{q-1} \overline{b_{q-1}}+b_{q}-b_{q-1}$ for $2 \leq q \leq g$. Recall that $n_{i}=l_{i-1} / l_{i}$, where $l_{i}=$ $\operatorname{gcd}\left(b_{0}, \ldots, b_{i}\right)=\operatorname{gcd}\left(\overline{b_{0}}, \ldots, \overline{b_{i}}\right)$.

Remember that the Milnor number of a curve $g(x, y)=0$ is by definition the intersection multiplicity $(\partial g / \partial x, \partial g / \partial y)_{0}$.

Theorem 2. Let $f=0$, where $f$ is an irreducible Weierstrass polynomial, be a branch with semigroup $\Gamma(f)=\left\langle\overline{b_{0}}, \ldots, \overline{b_{g}}\right\rangle$. Then the canonical decomposition of the $k$-th approximate Jacobian Newton diagram of $f$ is

$$
\mathcal{N}_{J}\left(f^{(k)}, f\right)=\left\{\frac{l_{k}\left(\mu\left(f^{(k)}\right)+\bar{m}-1\right)}{\mu\left(f^{(k)}\right)+\bar{m}-1}\right\}+\sum_{i=k+2}^{g}\left\{\frac{\left(n_{i}-1\right) \overline{b_{i}}}{\bar{m} n_{k+2} \cdots n_{i-1}\left(n_{i}-1\right)}\right\}
$$

where $\bar{m}=\overline{b_{k+1}} / l_{k+1}$, and $\mu\left(f^{(k)}\right)$ is the Milnor number of $f^{(k)}=0$.
Proof. In the course of the proof we shall use the canonical decomposition of $\mathcal{N}_{J}\left(f^{(k)}, f\right)$ from Corollary 1. We shall express all intersection multiplicities $\left(f, \Gamma^{(i)}\right)_{0}$ and $\left(f^{(k)}, \Gamma^{(i)}\right)_{0}$ for $k+1 \leq i \leq g$ in terms of the generators of the semigroup $\Gamma(f)$.

First consider $\Gamma^{(i)}$ for $k+2 \leq i \leq g$. By Theorem 1 the contact of every irreducible factor of $\Gamma^{(i)}$ with $f$ equals $b_{i} / b_{0}$. By Property 1 and Theorem 1:

$$
\begin{equation*}
\left(f, \Gamma^{(i)}\right)_{0}=\left(x, \Gamma^{(i)}\right)_{0} \frac{\left(f, \Gamma^{(i)}\right)_{0}}{\left(x, \Gamma^{(i)}\right)_{0}}=\left(x, \Gamma^{(i)}\right)_{0} \frac{\left(f, f^{(i-1)}\right)_{0}}{\left(x, f^{(i-1)}\right)_{0}}=\left(n_{i}-1\right) \overline{b_{i}} . \tag{3}
\end{equation*}
$$

By Corollary 1 and equality (2)

$$
\frac{\left(f, \Gamma^{(i)}\right)_{0}}{\left(f^{(k)}, \Gamma^{(i)}\right)_{0}}=\frac{\left(f, f^{(i-1)}\right)_{0}}{\left(f^{(k)}, f^{(i-1)}\right)_{0}}=\frac{(x, f)_{0}}{\left(f^{(k)}, f\right)_{0}} \cdot \frac{\left(f, f^{(i-1)}\right)_{0}}{\left(x, f^{(i-1)}\right)_{0}}=\frac{l_{i-1} \overline{b_{i}}}{\overline{b_{k+1}}} .
$$

Hence by (3)

$$
\left(f^{(k)}, \Gamma^{(i)}\right)_{0}=\frac{\overline{b_{k+1}}}{l_{i-1} \overline{b_{i}}}\left(f, \Gamma^{(i)}\right)_{0}=\bar{m} n_{k+2} \cdots n_{i-1}\left(n_{i}-1\right)
$$

In order to compute $\left(f^{(k)}, \Gamma^{(k+1)}\right)_{0}$ we use Theorem 3.2 of $[\mathbf{C a 1}]$. We get

$$
\left(f^{(k)}, \operatorname{jac}\left(f^{(k)}, f\right)\right)_{0}=\mu\left(f^{(k)}\right)+\left(f^{(k)}, f\right)_{0}-1
$$

Since $\left(f^{(k)}, \operatorname{jac}\left(f^{(k)}, f\right)\right)_{0}=\sum_{i=k+1}^{g}\left(f^{(k)}, \Gamma^{(i)}\right)_{0}$ we have

$$
\begin{aligned}
\left(f^{(k)}, \Gamma^{(k+1)}\right)_{0} & =\mu\left(f^{(k)}\right)+\left(f^{(k)}, f\right)_{0}-1-\sum_{i=k+2}^{g} \bar{m} n_{k+2} \cdots n_{i-1}\left(n_{i}-1\right) \\
& =\mu\left(f^{(k)}\right)+\overline{b_{k+1}}-1-\bar{m}\left(l_{k+1}-1\right)=\mu\left(f^{(k)}\right)+\bar{m}-1
\end{aligned}
$$

Finally by Corollary 1 and equality (1)

$$
\frac{\left(f, \Gamma^{(k+1)}\right)_{0}}{\left(f^{(k)}, \Gamma^{(k+1)}\right)_{0}}=\frac{(x, f)_{0}}{\left(x, f^{(k)}\right)_{0}}=l_{k}
$$

Hence $\left(f, \Gamma^{(k+1)}\right)_{0}=l_{k}\left(\mu\left(f^{(k)}\right)+\bar{m}-1\right)$.
REmark 1. In the above proof we compute the inclinations of elementary Newton diagrams of the canonical decomposition of $\mathcal{N}_{J}\left(f^{(k)}, f\right)$ which are equal to $\left(l_{i-1} \overline{b_{i}}\right) /\left(\overline{b_{k+1}}\right)$ for $i \in\{k+1, \ldots, g\}$. These inclinations are called Jacobian invariants.

Example 3. Let $f(x, y)=\left(y^{2}-x^{3}\right)^{2}-x^{5} y$. Then $f=0$ is a branch and $\Gamma(f)=\langle 4,6,13\rangle$. The characteristic approximate roots of $f$ are $f^{(0)}=y$ and $f^{(1)}=y^{2}-x^{3}$. The factorization of $\operatorname{jac}\left(f^{(0)}, f\right)$ described in Theorem 1 is $\operatorname{jac}\left(f^{(0)}, f\right)=\Gamma^{(1)} \Gamma^{(2)}$, where $\Gamma^{(1)}=x^{2}$ and $\Gamma^{(2)}=6 y^{2}+5 x^{2} y-6 x^{3}$. We also have $\operatorname{jac}\left(f^{(1)}, f\right)=x^{4}\left(10 y^{2}+3 x^{3}\right)$. Finally $\mathcal{N}_{J}\left(f^{(0)}, f\right)=\left\{\frac{8}{2}\right\}+\left\{\frac{13}{3}\right\}$ and $\mathcal{N}_{J}\left(f^{(1)}, f\right)=\left\{\frac{28}{14}\right\}$.

Corollary 2. The family of the approximate Jacobian Newton diagrams of a branch only depends on its topological type.

If $f$ is an irreducible Weierstrass polynomial then $f^{(0)}=0$ is a smooth curve. By Smith-Merle-Ephraim (see for example Theorem 2.2 of [GB-G2]) the approximate Jacobian Newton diagram $\mathcal{N}_{J}\left(f^{(0)}, f\right)$ determines the topological type of the branch $f=0$. Nevertheless we can also obtain the generators of the semigroup of the branch $f=0$ using the whole family of its approximate Jacobian Newton diagrams in an easy way: let $\Gamma(f)=\left\langle\overline{b_{0}}, \ldots, \overline{b_{g}}\right\rangle$ be the semigroup of $f=0$. It is clear that $\overline{b_{0}}$ is the smallest inclination of $\mathcal{N}_{J}\left(f^{(0)}, f\right)$. Denote by $\iota$ the inclination of the elementary diagram $\mathcal{N}_{J}\left(f^{(g-1)}, f\right)$. Put $\mathcal{H}_{r}$, for $r \in\{0, \ldots, g-2\}$, the height of the last elementary diagram of $\mathcal{N}_{J}\left(f^{(r)}, f\right)$, that is the height of the elementary diagram of $\mathcal{N}_{J}\left(f^{(r)}, f\right)$ which has the biggest inclination. Then $\bar{b}_{r+1}=\iota \mathcal{H}_{r} /(\iota-1)$ for $r \in\{0, \ldots, g-2\}$. Finally $\bar{b}_{g}=\mathcal{L} /(\iota-1)$, where $\mathcal{L}$ is the length of the last elementary diagram of $\mathcal{N}_{J}\left(f^{(g-2)}, f\right)$.

Example 4. Consider the branches $f_{i}=0$ for $i \in\{1, \ldots, 4\}$ with semigroups $\Gamma\left(f_{1}\right)=\langle 4,14,31\rangle, \Gamma\left(f_{2}\right)=\langle 4,6,35\rangle, \Gamma\left(f_{3}\right)=\langle 4,6,37\rangle$ and $\Gamma\left(f_{4}\right)=\langle 6,10,31\rangle$. By Theorem 2 we have $\mathcal{N}_{J}\left(f_{1}^{(1)}, f_{1}\right)=\mathcal{N}_{J}\left(f_{2}^{(1)}, f_{2}\right)=\left\{\frac{72}{36}\right\}$ and $\mathcal{N}_{J}\left(f_{3}^{(1)}, f_{3}\right)=$ $\mathcal{N}_{J}\left(f_{4}^{(1)}, f_{4}\right)=\left\{\frac{76}{38}\right\}$.

Given a branch $f=0$, put $\mathcal{F}$ its family of approximate Jacobian Newton diagrams but the first one. The example shows that $\mathcal{F}$ is not a complete topological
invariant of a branch. The curves $f_{3}=0$ and $f_{4}=0$ have the same $\mathcal{F}$ but they have different multiplicities at the origin. The curves $f_{1}=0$ and $f_{2}=0$ have the same $\mathcal{F}$ and the same multiplicity at the origin but in spite of it they have different topological type.

## 5. Proof of Theorem 1.

Let $\tau$ be a positive rational number and let $g(x, y)=\sum_{i \in \mathbf{Q}, j \in \boldsymbol{N}} a_{i j} x^{i} y^{j} \in$ $\boldsymbol{C}\{x\}^{*}[y]$. Put $w(x):=1$ and $w(y):=\tau$ the weights of the variables $x$ and $y$. By definition the weighted order of $g$ is $\operatorname{ord}_{\tau}(g)=\min \left\{i+\tau j: a_{i j} \neq 0\right\}$ and the


Lemma 1. Let $g(x, y)=u(x, y) \cdot x^{N} \prod_{i=1}^{d}\left(y-\alpha_{i}(x)\right)$, where $u(0,0) \neq 0$, $N \in \boldsymbol{Q}, \alpha_{i}(x)=c_{i} x^{\tau}+\cdots$ for $1 \leq i \leq k$ and $\operatorname{ord}_{x}\left(\alpha_{i}(x)\right)<\tau$, for $k+1 \leq i \leq d$. Then $\operatorname{in}_{\tau}(g)=c x^{M} \prod_{i=1}^{k}\left(y-c_{i} x^{\tau}\right)$ for some $c \in \boldsymbol{C}$ and some $M \in \boldsymbol{Q}$.

Proof. Observe that $\operatorname{in}_{\tau}\left(y-\alpha_{i}(x)\right)=y-c_{i} x^{\tau}$ for $1 \leq i \leq k$ and $\operatorname{in}_{\tau}(y-$ $\left.\alpha_{i}(x)\right)=-\operatorname{in}_{\tau} \alpha_{i}(x)$ for $k+1 \leq i \leq d$. Since the initial part of a product is the product of the initial parts of every factor we get the lemma.

Lemma 2. Let $h_{1}, h_{2} \in \boldsymbol{C}\{x\}^{*}[y]$ and $\tau \in \boldsymbol{Q}^{+}$. Assume that the Jacobian $\operatorname{jac}\left(\operatorname{in}_{\tau}\left(h_{1}\right), \operatorname{in}_{\tau}\left(h_{2}\right)\right) \neq 0$. Then $\operatorname{in}_{\tau}\left(\operatorname{jac}\left(h_{1}, h_{2}\right)\right)=\operatorname{jac}\left(\operatorname{in}_{\tau}\left(h_{1}\right), \operatorname{in}_{\tau}\left(h_{2}\right)\right)$.

Proof. For all monomials $M_{1}=x^{i_{1}} y^{j_{1}}$ and $M_{2}=x^{i_{2}} y^{j_{2}}$ we have $\operatorname{jac}\left(M_{1}, M_{2}\right)=\left(i_{1} j_{2}-i_{2} j_{1}\right) x^{i_{1}+i_{2}-1} y^{j_{1}+j_{2}-1}$ hence $\operatorname{ord}_{\tau}\left(\operatorname{jac}\left(M_{1}, M_{2}\right)\right)=$ $\operatorname{ord}_{\tau}\left(M_{1}\right)+\operatorname{ord}_{\tau}\left(M_{2}\right)-1-\tau$ provided $i_{1} j_{2}-i_{2} j_{1} \neq 0$. It follows that $\operatorname{jac}\left(\operatorname{in}_{\tau}\left(h_{1}\right), \operatorname{in}_{\tau}\left(h_{2}\right)\right)$ is the sum of monomials of the same weighted order $\operatorname{ord}_{\tau}\left(\operatorname{in}_{\tau}\left(h_{1}\right)\right)+\operatorname{ord}_{\tau}\left(\operatorname{in}_{\tau}\left(h_{2}\right)\right)-1-\tau$ (that is a quasi-homogeneous polynomial). Moreover $\operatorname{jac}\left(h_{1}, h_{2}\right)=\operatorname{jac}\left(\operatorname{in}_{\tau}\left(h_{1}\right)+\left(h_{1}-\operatorname{in}_{\tau}\left(h_{1}\right)\right), \operatorname{in}_{\tau}\left(h_{2}\right)+\left(h_{2}-\operatorname{in}_{\tau}\left(h_{2}\right)\right)\right)=$ $\operatorname{jac}\left(\mathrm{in}_{\tau}\left(h_{1}\right), \mathrm{in}_{\tau}\left(h_{2}\right)\right)+$ terms of higher weighted order which proves the lemma.

Recall that Newton-Puiseux roots of an irreducible Weierstrass polynomial $f \in \boldsymbol{C}\{x\}[y], \operatorname{deg} f=n$ form a cycle: if $\gamma(x)=\sum a_{i} x^{i / n}$ is a root of $f$ then other roots of $f$ are $\gamma_{j}(x)=\sum a_{i} \omega_{j}^{i} x^{i / n}$, where $\omega_{j}$ is a $n$-th root of unity. Moreover $\operatorname{ord}_{x}\left(\gamma(x)-\gamma_{j}(x)\right) \geq b_{k+1} / b_{0}$ if and only if $\omega_{j}$ is a $l_{k}$-th root of unity (see $[\mathbf{Z}]$ ).

Let $f=\prod_{i=1}^{n}\left(y-\gamma_{i}(x)\right)$ be an irreducible Weierstrass polynomial with Puiseux characteristic $\left(b_{0}, \ldots, b_{g}\right)$ and let $f^{(k)}(x, y)=\prod_{j=1}^{m}\left(y-\delta_{j}(x)\right)$, where $n=m l_{k}$, be the characteristic approximate root of $f$. Put $J(x, y):=\operatorname{jac}\left(f^{(k)}, f\right)=$ unity $\cdot x^{\alpha} \prod_{l}\left(y-\sigma_{l}(x)\right)$. In order to prove Theorem 1 we need

Lemma 3. Fix $\gamma \in \operatorname{Zer} f$ and $\tau \in \boldsymbol{Q}$ such that $\tau \geq b_{k+1} / b_{0}$. Then

1. if $b_{j} / b_{0}<\tau \leq b_{j+1} / b_{0}$, where $j \in\{k+1, \ldots, g\}$ then $\sharp\left\{i: \mathcal{O}\left(\sigma_{i}, \gamma\right) \geq \tau\right\}=l_{j}-1$, 2. if $\tau=b_{k+1} / b_{0}$ then $\sharp\left\{i: \mathcal{O}\left(\sigma_{i}, \gamma\right) \geq \tau\right\}=n_{k+1}\left(l_{k+1}-1\right)$.

Proof. Let $\tilde{J}(x, y):=J(x, y+\gamma(x)), \tilde{f}(x, y):=f(x, y+\gamma(x))$ and $\tilde{f}^{(k)}(x, y):=f^{(k)}(x, y+\gamma(x))$. Clearly $\tilde{J}(x, y)=$ unity $\cdot x^{\alpha} \prod_{l}\left(y-\left(\sigma_{l}(x)-\gamma(x)\right)\right)$. By Lemma $1 \sharp\left\{i: \mathcal{O}\left(\sigma_{i}, \gamma\right) \geq \tau\right\}=\operatorname{deg}_{y}\left(\operatorname{in}_{\tau}(\tilde{J}(x, y))\right)$.

Assume first that $\tau>b_{k+1} / b_{0}$ and $\tau \neq b_{j} / b_{0}$ for all $j \in\{k+2, \ldots, g\}$. The weighted initial part of $\tilde{f}(x, y)=\prod_{i=1}^{n}\left(y-\left(\gamma_{i}(x)-\gamma(x)\right)\right)$ is equal to $\mathrm{in}_{\tau}(\tilde{f}(x, y))=$ $c_{1} x^{\alpha_{1}} y^{d(\tau)}$, where $c_{1} \in \boldsymbol{C} \backslash\{0\}$ and $d(\tau):=\sharp\left\{i: \mathcal{O}\left(\gamma_{i}, \gamma\right) \geq \tau\right\}$. More precisely if $b_{j} / b_{0}<\tau<b_{j+1} / b_{0}$ then $d(\tau)=l_{j}$.

Consider the function $\tilde{f}^{(k)}(x, y)=\prod_{j=1}^{m}\left(y-\left(\delta_{j}(x)-\gamma(x)\right)\right)$. Since $\mathcal{O}\left(\delta_{j}, \gamma\right)<$ $\tau$ for every $j \in\{1, \ldots, m\}$, we get by Lemma $1 \operatorname{in}_{\tau} \tilde{f}^{(k)}(x, y)=c_{2} x^{\alpha_{2}}$, where $c_{2} \in \boldsymbol{C} \backslash\{0\}$.

Using Lemma 2 we get

$$
\operatorname{in}_{\tau}(\tilde{J}(x, y))=\operatorname{jac}\left(c_{2} x^{\alpha_{2}}, c_{1} x^{\alpha_{1}} y^{d(\tau)}\right)=c_{1} c_{2} \alpha_{2} d(\tau) x^{\alpha_{1}+\alpha_{2}-1} y^{d(\tau)-1}
$$

so its $y$-degree is equal to $d(\tau)-1=l_{j}-1$ for $b_{j} / b_{0}<\tau<b_{j+1} / b_{0}$.
Let us choose $\tau<b_{j+1} / b_{0}$ close enough to $b_{j+1} / b_{0}$ that no $\sigma_{i}$ satisfies $\tau \leq$ $\mathcal{O}\left(\sigma_{i}, \gamma\right)<b_{j+1} / b_{0}$. Then $\sharp\left\{i: \mathcal{O}\left(\sigma_{i}, \gamma\right) \geq \tau\right\}=\sharp\left\{i: \mathcal{O}\left(\sigma_{i}, \gamma\right) \geq b_{j+1} / b_{0}\right\}$ and the proof of statement 1 is done.

Assume now that $\tau=b_{k+1} / b_{0}$. By Lemma 1

$$
\begin{aligned}
\operatorname{in}_{\tau} \tilde{f}(x, y) & =x^{\alpha_{3}} \prod_{\omega^{l_{k}}=1}\left(y-a\left(\omega^{b_{k+1}}-1\right) x^{b_{k+1} / b_{0}}\right) \\
& =x^{\alpha_{3}} \prod_{\omega^{l_{k}}=1}\left[\left(y+a x^{b_{k+1} / b_{0}}\right)-a \omega^{b_{k+1}} x^{b_{k+1} / b_{0}}\right] \\
& =x^{\alpha_{3}}\left[\left(y+a x^{b_{k+1} / b_{0}}\right)^{n_{k+1}}-\left(a x^{b_{k+1} / b_{0}}\right)^{n_{k+1}}\right]^{l_{k+1}}
\end{aligned}
$$

where $\omega \in \boldsymbol{C}$ and $a$ is the coefficient in $\gamma$ of the term $x^{b_{k+1} / b_{0}}$. The last equality follows from the formula $\prod_{\omega^{p}=1}\left(Z-b \omega^{q}\right)=\left(Z^{p / \operatorname{gcd}(p, q)}-b^{p / \operatorname{gcd}(p, q)}\right) \operatorname{gcd}(p, q)$.

Moreover and also using Lemma 1 we have $\operatorname{in}_{\tau} \tilde{f}^{(k)}(x, y)=x^{\alpha_{4}}\left(y+a x^{b_{k+1} / b_{0}}\right)$ since there is only one Newton-Puiseux root $\delta_{j}$ of $f^{(k)}$ such that $\mathcal{O}\left(\delta_{j}, \gamma\right) \geq b_{k+1} / b_{0}$ (otherwise if there were two of such roots $\delta_{j_{1}}, \delta_{j_{2}}$ then by the triangular property of the contact order we obtain $\mathcal{O}\left(\delta_{j_{1}}, \delta_{j_{2}}\right) \geq b_{k+1} / b_{0}$ which is not possible).

We prove now the equality $\alpha_{3}=\alpha_{4} l_{k}$. Note that $\alpha_{3}=\sum_{i \in I^{\prime}} \mathcal{O}\left(\gamma_{i}, \gamma\right)$ and $\alpha_{4}=\sum_{j \in J^{\prime}} \mathcal{O}\left(\delta_{j}, \gamma\right)$, where $I^{\prime}:=\left\{i: \mathcal{O}\left(\gamma_{i}, \gamma\right)<b_{k+1} / b_{0}\right\}$ and $J^{\prime}:=$ $\left\{j: \mathcal{O}\left(\delta_{j}, \gamma\right)<b_{k+1} / b_{0}\right\}$. Using Puiseux characteristic of $f$ and after Sec-
tion 3 in [G-Pł3] we obtain $\alpha_{3}=\sum_{i \in I^{\prime}} \mathcal{O}\left(\gamma_{i}, \gamma\right)=\sum_{l=1}^{k} \sharp\left\{i: \mathcal{O}\left(\gamma_{i}, \gamma\right)=\right.$ $\left.b_{l} / b_{0}\right\} \cdot b_{l} / b_{0}=\left(n-l_{1}\right) b_{1} / b_{0}+\cdots+\left(l_{k-1}-l_{k}\right) b_{k} / b_{0}$ and by the same argument $\alpha_{4}=\sum_{j \in J^{\prime}} \mathcal{O}\left(\delta_{j}, \gamma\right)=\left(n / l_{k}-l_{1} / l_{k}\right) b_{1} / b_{0}+\cdots+\left(l_{k-1} / l_{k}-1\right) b_{k} / b_{0}$.

Finally the initial part of $\tilde{J}$ is

$$
\operatorname{in}_{\tau}(\tilde{J})=\operatorname{jac}\left(\operatorname{in}_{\tau}(\tilde{f}(k)), \operatorname{in}_{\tau}(\tilde{f})\right)=\operatorname{jac}\left(v,\left(v^{n_{k+1}}-a^{n_{k+1}} u^{\theta}\right)^{l_{k+1}}\right),
$$

where $v=x^{\alpha_{4}}\left(y+a x^{b_{k+1} / b_{0}}\right), u=x$ and $\theta=n_{k+1}\left(b_{k+1} / b_{0}+\alpha_{4}\right)$ so $\mathrm{in}_{\tau}(\tilde{J})=$ $\partial \mathrm{in}_{\tau}(\tilde{f}) / \partial u \cdot \partial v / \partial y$ and its $y$-degree is equal to $n_{k+1}\left(l_{k+1}-1\right)$.

Remark 2. The proof of Merle formula in [G-Pł1] was based on the equality $\Delta_{\tilde{f}}=\Delta_{\tilde{j}}+\left\{\frac{\infty}{\mathrm{T}}\right\}$, where $\tilde{j}(x, y)=j(x, y+\gamma(x))$ and $j(x, y):=\mathrm{jac}(x, f)$. Note that the statement of Lemma 3 can be written as $\operatorname{deg}_{y} \operatorname{in}_{\tau}(\tilde{J}(x, y))=\operatorname{deg}_{y} \operatorname{in}_{\tau}(\tilde{f}(x, y))-$ 1 for $\tau>b_{k+1} / b_{0}$. It follows from this equality that $\tilde{\Delta}_{\tilde{f}}=\tilde{\Delta}_{\tilde{J}}+\left\{\frac{\infty}{\tau}\right\}$, where $\tilde{\Delta}_{\tilde{J}}$ and $\tilde{\Delta}_{\tilde{f}}$ are the sums of elementary Newton diagrams in the canonical decompositions of $\Delta_{\tilde{J}}$ and $\Delta_{\tilde{f}}$ respectively with inclinations bigger than $b_{k+1} / b_{0}$.

Corollary 3. Keep the above notations and put $\tau_{i}:=\operatorname{cont}\left(\sigma_{i}, f\right)$. Then

1. if $\tau_{i} \geq b_{k+1} / b_{0}$ then $\tau_{i} \in\left\{b_{k+2} / b_{0}, \ldots, b_{g} / b_{0}\right\}$.
2. The number $\sharp\left\{i: \tau_{i}=b_{j} / b_{0}\right\}=n_{1} \cdots n_{j-1}\left(n_{j}-1\right)$ for $j \in\{k+2, \ldots, g\}$.

Proof. First take $\tau$ such that $b_{j} / b_{0}<\tau \leq b_{j+1} / b_{0}$ for $k+1 \leq j \leq g$. We shall prove that

$$
\begin{equation*}
\sharp\left\{i: \tau_{i} \geq \tau\right\}=n-n_{1} \cdots n_{j} . \tag{4}
\end{equation*}
$$

In the set Zer $f$ we define the equivalence relation given by

$$
\gamma^{*} \equiv \gamma^{\prime} \text { if and only if } \mathcal{O}\left(\gamma^{*}, \gamma^{\prime}\right) \geq \frac{b_{j+1}}{b_{0}}
$$

Put $I_{\gamma}:=\left\{i: \mathcal{O}\left(\sigma_{i}, \gamma\right) \geq \tau\right\}$ for $\gamma \in \operatorname{Zer} f$. By Lemma 3 we get $\sharp I_{\gamma}=l_{j}-1$. Note that $I_{\gamma^{\prime}}=I_{\gamma^{*}}$ for $\gamma^{*} \equiv \gamma^{\prime}$ and $I_{\gamma^{\prime}} \cap I_{\gamma^{*}}=\emptyset$ when $\gamma^{*} \not \equiv \gamma^{\prime}$.

Remark that $n_{1} \cdots n_{j}$ is the number of cosets in the equivalence relation $\equiv$. Since $\sharp\left\{i: \tau_{i} \geq \tau\right\}=\bigcup_{\gamma \in \operatorname{Zer} f} I_{\gamma}$ we have $\sharp\left\{i: \tau_{i} \geq \tau\right\}=n_{1} \cdots n_{j} \cdot \sharp I_{\gamma}=$ $n_{1} \cdots n_{j}\left(l_{j}-1\right)=n-n_{1} \cdots n_{j}$. The equality (4) is proved.

Fix small positive number $\epsilon$ such that

$$
\sharp\left\{i: \tau_{i}=\tau\right\}=\sharp\left\{i: \tau_{i} \geq \tau\right\}-\sharp\left\{i: \tau_{i} \geq \tau+\epsilon\right\} .
$$

If $\tau \neq b_{j} / b_{0}$ for all $j \in\{k+2, \ldots, g\}$ the above difference is equal to zero. If $\tau=b_{j} / b_{0}$ for some $j \in\{k+2, \ldots, g\}$, then $\sharp\left\{i: \tau_{i}=b_{j} / b_{0}\right\}=\left(n-n_{1} \cdots n_{j-1}\right)-$ $\left(n-n_{1} \cdots n_{j}\right)=n_{1} \cdots n_{j-1}\left(n_{j}-1\right)$.

Finally using the same argument as before (for $\tau=b_{k+1} / b_{0}$ ) we have

$$
\begin{aligned}
\sharp\left\{i: \tau_{i}=\frac{b_{k+1}}{b_{0}}\right\} & =\sharp\left\{i: \tau_{i} \geq \frac{b_{k+1}}{b_{0}}\right\}-\sharp\left\{i: \tau_{i} \geq \frac{b_{k+1}}{b_{0}}+\epsilon\right\} \\
& =\sharp\left\{i: \tau_{i} \geq \frac{b_{k+1}}{b_{0}}\right\}-\left(n-n_{1} \cdots n_{k+2}\right) \\
& =n_{k+1}\left(l_{k+1}-1\right) n_{1} \cdots n_{k}-\left(n-n_{1} \cdots n_{k+1}\right)=0 .
\end{aligned}
$$

Proof of Theorem 1. Let $k+2 \leq j \leq g$. Put $\Gamma^{(j)}=\Pi\left(y-\sigma_{i}(x)\right)$, where the product runs over $\sigma_{i}$ with $\operatorname{cont}\left(\sigma_{i}, f\right)=b_{j} / b_{0}$ and let $\Gamma^{(k+1)}=$ $\operatorname{jac}\left(f^{(k)}, f\right) /\left(\Gamma^{(k+2)} \cdots \Gamma^{(g)}\right)$. It follows from the first statement of Corollary 3 that for every Newton-Puiseux root $\alpha \in \operatorname{Zer} \Gamma^{(k+1)}$ we have $\operatorname{cont}(\alpha, f)<b_{k+1} / b_{0}$. Finally by the second statement of Corollary 3 we get $\left(\Gamma^{(i)}, x\right)_{0}=n_{1} \cdots n_{i-1}\left(n_{i}-1\right)$ for $k+2 \leq i \leq g$.

## 6. Relation with Michel's theorem.

In $[\mathbf{M i}]$ the author considered a finite morphism $(f, g):(X, p) \longrightarrow\left(C^{2}, 0\right)$, where $(X, p)$ is a normal germ of complex surface. Michel determined the Jacobian quotients via a good minimal resolution and pointed out the importance of the multiplicities of the Jacobian quotients. More precisely and following notation of [Mi], let $R$ be a good resolution of $(f, g)$ and put $E=R^{-1}(p)$ the exceptional divisor of $R$. For every irreducible component $E_{i}$ of $E$, denote $E_{i}^{\prime}$ the set of points of $E_{i}$ which are smooth points of the total transform $\tilde{E}=R^{-1}\left((f g)^{-1}(0)\right)$. Denote the order of $f \circ R$ (respectively $g \circ R$ ) at a generic point of $E_{i} v\left(f, E_{i}\right)$ (respectively $\left.v\left(g, E_{i}\right)\right)$. The quotient $q_{i}=v\left(g, E_{i}\right) / v\left(f, E_{i}\right)$ is the Hironaka number of $E_{i}$.

Let $q$ be a Hironaka number and put $E(q)$ the union of the $E_{i}^{\prime}$ such that $q_{i}=q$ to which we add $E_{i} \cap E_{j}$ if $q_{i}=q_{j}=q$. Let $\left\{E^{k}(q)\right\}_{k}$ be the connected components of $E(q)$. By definition a $q$-zone is a connected component of $E(q)$ and a $q$-zone is a rupture zone if there exists in it at least one $E_{i}^{\prime}$ with negative Euler characteristic. Then after Theorem 4.8 of $[\mathbf{M i}]$ the set of Jacobian invariants of the morphism $(f, g)$ is equal to the set of Hironaka numbers $q$ such that there exists at least one $q$-zone in $E$ which is a rupture zone.

Consider an irreducible Weierstrass polynomial $f$ with Puiseux characteristic $\left(b_{0}, b_{1}, \ldots, b_{g}\right)$, where $b_{0}<b_{1}$ (i.e. $x=0$ is transverse to $f=0$ ). Below is the schematic picture of the resolution graph of the curve $f^{(k)} f=0$.


Every Jacobian invariant $q \in\left\{l_{k}, l_{k+1} \overline{b_{k+2}} / \overline{b_{k+1}}, \ldots, l_{g-1} \overline{b_{g}} / \overline{b_{k+1}}\right\}$ of the mor$\operatorname{phism}\left(f^{(k)}, f\right)$ corresponds to exactly one rupture zone.

The rupture zone for $q=l_{k}$ is the tree with endpoints $F_{0}, F_{k+1}, L_{1}, \ldots, L_{k}$. It yields the factor $\Gamma^{(k+1)}$ of the Jacobian and by Michel's theorem $\left(\Gamma^{(k+1)}, h\right)_{0}=$ $\sum_{i=1}^{k+1} v\left(h, F_{i}\right)-\sum_{i=1}^{k} v\left(h, L_{i}\right)-v\left(h, F_{0}\right)$, where $h=f$ or $h=f^{(k)}$.

Every rupture zone for $q=l_{i-1} \overline{b_{i}} / \overline{b_{k+1}}$, where $k+2 \leq i \leq g$ is the bamboo with endpoints $F_{i}$ and $L_{i}$. It yields the factor $\Gamma^{(i)}$ of the Jacobian and by Michel's theorem $\left(\Gamma^{(i)}, h\right)_{0}=v\left(h, F_{i}\right)-v\left(h, L_{i}\right)$ for $k+2 \leq i \leq g$, where $h=f$ or $h=f^{(k)}$.

As an illustration we draw the resolution graph of $f^{(0)} f=0$, where $f$ is the Weierstrass polynomial from Example 3. The labels of divisors are Hironaka numbers written in the form $v\left(f, E_{i}\right) / v\left(f^{(0)}, E_{i}\right)$.


There are two rupture zones corresponding to Hironaka numbers 4 and 13/3. It follows from $[\mathbf{M i}]$ that $\mathcal{N}_{J}\left(f^{(0)}, f\right)=\left\{\frac{12}{3}\right\}-\left\{\frac{4}{1}\right\}+\left\{\frac{26}{6}\right\}-\left\{\frac{13}{3}\right\}=\left\{\frac{8}{2}\right\}+\left\{\frac{13}{3}\right\}$.

Remark 3. Remark that Theorem 1 is also true when we change $f^{(k)}$ for any irreducible Weierstrass polynomial with the properties of statement of Proposition 2.

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